

## Business Intelligence and Analytics

# Evaluation 

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## (Data Mining)

## CRISP-DM Methodology



## How to evaluate a model?

- Select a training set
- Build a mining model
- Choose a quality measure
- Select a test set
- Apply the model on the test set
- Compute the value of the quality measure


## A simple evaluation schema



## The fitting problem

- Beyond the data analysis issues, there are challenges even in the modeling and evaluate phases in the CRISP-DM Methodology
- Namely
- Underfitting
- The model is too simple: the evaluation will be poor on both the training and the evaluation set
- Overfitting
- The model is too complex, fitting as close as it can the training data, the evaluation will be good on the training set, but poor on the evaluation set


## Overfitting (due to noise)



## Overfitting (due to lack of information)



## Overfitting



## How to mitigate the overfittig?

- Prevention
- A good data preparation
- Avoiding
- Feed the building phase with further data for improving the model's generality (e.g. online pruning)
- Recovery
- Manipulate the model after its creation (e.g. post pruning)


## How to mitigate the overfittig?



## How to evaluate a model?

- Is a model that achieves $70 \%$ of global accuracy a "good" model?


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- It depends...


## How to evaluate a model?

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- Is a model that achieves $95 \%$ of global accuracy a "good" model?


## How to evaluate a model?

- Is a model that achieves 70\% of global accuracy a "good" model?
- It depends...
- Is a model that achieves $95 \%$ of global accuracy a "good" model?
- It depends...


## How to evaluate a model?

- We can perform only comparative evaluations.
- A "null hypothesis" (in other words, a baseline) is needed.
- We can only say, given a statistic, if a model is better then another one, in terms of the chosen statistic.


## True and estimated error

o The "true" error of a hypothesis $h$ in the domain $D$

$$
e_{\text {true }}(h)=\operatorname{Pr}_{\mathrm{x} \in D}(c(x) \neq h(x))
$$

- The estimated (observed) error on a data set S

$$
e_{\text {estimation }}(h)=\frac{1}{|S|} \sum_{x \in S} e(x)
$$

o Where:

$$
e(x)= \begin{cases}1 & \text { if } c(x) \neq h(x) \\ 0 & \text { otherwise }\end{cases}
$$

## True Error

- The probability of (exactly) r misclassifications in $n$ evaluations is governed by a binomial distribution:



## True Error - Binomial Distribution

- Probability Mass Distribution

$$
\operatorname{Pr}(r)=\frac{n!}{r!(n-r)!} e_{\text {true }}(h)^{r}\left(1-e_{\text {true }}(h)\right)^{n-r}
$$

- Cumulative Distribution Function

$$
\operatorname{Pr}(a \leq r \leq b)=\sum_{r=a}^{b} \frac{n!}{r!(n-r)!} e_{\text {true }}(h)^{r}\left(1-e_{\text {true }}(h)\right)^{n-r}
$$

- Expected Value

$$
E[R]=n \cdot e_{\text {true }}(h)
$$

- Variance \& Standard Deviation

$$
\operatorname{Var}[R]=n \cdot e_{\text {true }}(h) \cdot\left[1-e_{\text {true }}(h)\right] \quad \operatorname{sd}[R]=\sqrt{\operatorname{Var}[R]}
$$

## Estimated Error

- Given a set of data $S$

$$
e_{\text {estimation }}(h)=\frac{1}{|S|} \sum_{x \in S} e(x)
$$

- Where e(x) are independent and identically distributed (i.i.d.) Bernoullian random variables:

$$
e(x)= \begin{cases}1 & \text { if } c(x) \neq h(x) \\ 0 & \text { otherwise }\end{cases}
$$

$$
e(x) \sim \text { Bernoulli }\left(e_{\text {true }}(h)\right)
$$

## Bernoulli Distribution

- Probability Mass Distribution

$$
\operatorname{Pr}\left(e(x) ; e_{\text {true }}(h)\right)=e_{\text {true }}(h)^{e(x)}\left(1-e_{\text {true }}(h)\right)^{1-e(x)}
$$

- Expected Value

$$
E[e(X)]=e_{\text {true }}
$$

- Variance \& Standard Deviation

$$
\operatorname{Var}[e(X)]=e_{\text {true }}(h) \cdot\left[1-e_{\text {true }}(h)\right] \quad \operatorname{sd}[e(X)]=\sqrt{\operatorname{Var}[e(X)]}
$$

## Estimated Error Distribution

- From the probability theory, the sum of i.i.d. Bernoulli variables is governed by a binomial distribution
- Proof by induction:
http://www.statlect.com/uddbin 1.htm
- $e_{\text {estimation }}(h)$ is also a binomial distribution

$$
\begin{aligned}
e_{\text {estimation }}(h)=\frac{1}{|S|} & \sum_{x \in S} e(x) \\
& e_{\text {estimation }}(h) \sim \operatorname{Binomial}\left(|S|, e_{\text {true }}(h)\right)
\end{aligned}
$$

## Estimated Error Expected Value \& Variance

- Expected Value:

$$
\begin{aligned}
E\left[e_{\text {estimation }}(h)\right] & =E\left[\frac{1}{|S|} \sum_{x \in S} e(x)\right]=\frac{1}{|S|} \sum_{x \in S} E[e(x)] \\
& =E[e(x)]=e_{\text {true }}(H)
\end{aligned}
$$

- Variance:
$\operatorname{Var}\left[e_{\text {estimation }}(h)\right]=\operatorname{Var}\left[\frac{1}{|S|} \sum_{x \in S} e(x)\right]=\frac{1}{|S|^{2}} \sum_{x \in S} \operatorname{Var}[e(x)]$

$$
=\frac{1}{|S|} \operatorname{Var}[e(x)]=\frac{1}{|S|} e_{\text {true }}(h) \cdot\left[1-e_{\text {true }}(h)\right]
$$

## Summary 1/2

- There exists a link between the true error and the estimated error, if the data set $S$ is representative of its domain
- The strong law of large numbers

$$
\begin{aligned}
& \operatorname{Pr}\left(\lim _{|S| \rightarrow \infty} \frac{1}{|S|} \sum_{x \in S} e(x)=e_{\text {true }}(h)\right)=1 \\
& \lim _{|S| \rightarrow \infty} e_{\text {estimation }}(h)=e_{\text {true }}(h) \quad \text { almost surely }
\end{aligned}
$$

## Summary 2/2

- The estimated error is a binomial distribution, if $|S|$ is great "enough":

$$
E\left[e_{\text {estimation }}(h)\right]=e_{\text {true }}(h) \approx e_{\text {estimation }}(h)
$$

$\operatorname{Var}\left[e_{\text {estimation }}(h)\right]=\frac{e_{\text {true }}(h) \cdot\left[1-e_{\text {true }}(h)\right]}{|S|} \approx \frac{e_{\text {estimation }}(h) \cdot\left[1-e_{\text {estimation }}(h)\right]}{|S|}$

$$
\operatorname{sd}\left[e_{\text {estimation }}(h)\right]=\sqrt{\operatorname{Var}\left[e_{\text {estimation }}(h)\right]} \approx \sqrt{\frac{e_{\text {estimation }}(h) \cdot\left[1-e_{\text {estimation }}(h)\right]}{|S|}}
$$

## Binomial - Normal Approximation

- If $|S|$ is sufficient great (typically $|S|>30$ ) the binomial distribution can be approximated by a normal distribution
o Central limit theorem
- "states that the distribution of the sum (or average) of a large number of independent, identically distributed variables will be approximately normal, regardless of the underlying distribution."


## Normal Distribution

o Normal distribution


## Normal Distribution

o Normal distribution

- Density

$$
f(x)=\frac{1}{\sqrt{2 \pi} \sigma} \exp \left\{-\frac{(x-\mu)^{2}}{2 \sigma^{2}}\right\}
$$

- Cumulative

$$
\operatorname{Pr}(a \leq X \leq b)=\int_{a}^{b} f(x) d x
$$

- Expected Value

$$
E[X]=\mu
$$

o Variance

$$
\operatorname{Var}[X]=\sigma
$$

## Mean and Variance Approximation

- Due to the binomial - normal approximation

$$
\mu \approx e_{\text {estimation }}(h)
$$

$$
\sigma^{2} \approx \frac{e_{\text {estimation }}(h) \cdot\left[1-e_{\text {estimation }}(h)\right]}{|S|}
$$

$$
\sigma \approx \sqrt{\frac{e_{\text {estimation }}(h) \cdot\left[1-e_{\text {estimation }}(h)\right]}{|S|}}
$$

## Why are we interested in the Normal distribution?

- Confidence Intervals
- Given a probability $\alpha$, we are interested in finding an interval [a, b] such that

$$
\operatorname{Pr}(a \leq X \leq b)=\gamma
$$



- In the normal case

$$
\operatorname{Pr}\left(\mu-z_{n} \sigma \leq X \leq \mu+z_{n} \sigma\right)=\gamma
$$

| $\gamma$ | $50 \%$ | $68 \%$ | $80 \%$ | $90 \%$ | $95 \%$ | $98 \%$ | $99 \%$ |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $Z_{N}$ | 0.67 | 1.00 | 1.28 | 1.64 | 1.96 | 2.33 | 2.58 |

## Why are we interested in the Normal distribution?

- This means that the true error is in the interval

$$
e_{\text {true }}(h) \in\left\{e_{\text {estimation }}(h) \pm z_{n} \sqrt{\frac{e_{\text {estimation }}(h) \cdot\left[1-e_{\text {estimation }}(h)\right]}{|S|}}\right\}
$$

- With probability $\gamma$

| $\gamma$ | $50 \%$ | $68 \%$ | $80 \%$ | $90 \%$ | $95 \%$ | $98 \%$ | $99 \%$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $Z_{N}$ | 0.67 | 1.00 | 1.28 | 1.64 | 1.96 | 2.33 | 2.58 |

## How to compare models?

- Consider two hypothesis $h$ and $j \ldots$
- ... and the random variable

$$
d=e(h)-e(j)
$$

- It's governed by a binomial distribution
- Choose $z_{n}$ and consequently $\gamma$


## How to compare models?

o Three cases:

$$
d=e(h)-e(j)
$$

o Zero is in the confidence interval of $d$

- There is no statistical difference between $h$ and $j$, with significance $\boldsymbol{\gamma}$
- The confidence interval of $d$ is under Zero - e(h) is statistically lower than $\mathrm{e}(\mathrm{j})$, with significance $\gamma$
- The confidence interval of $d$ is above Zero - e(h) is statistically higher than e(j), with significance $\gamma$

$$
\operatorname{Pr}\left(\mu-z_{n} \sigma \leq X \leq \mu+z_{n} \sigma\right)=\gamma
$$

## How to compare models?

o Where:

$$
\mu=\left|e_{\text {estimation }}(h)-e_{\text {estimation }}(j)\right|
$$

- And, since the hypothesis are independent:

$$
\sigma^{2}=\operatorname{Var}\left[e_{\text {estimation }}(h)\right]+\operatorname{Var}\left[e_{\text {estimation }}(j)\right]
$$

## Evaluation Example

o Let
o e(h) $=0.15$, with $\left|S_{1}\right|=30$

- e(j) $=0.25$, with $\left|S_{2}\right|=5000$
o Then:
od = |e(h) $-e(j) \mid$


## Evaluation Example

- The expected value:

$$
\mu=\left|e_{\text {estimation }}(h)-e_{\text {estimation }}(j)\right|=|0.15-0.25|=0.1
$$

- The standard deviation:

$$
\begin{aligned}
& \sigma^{2}=\frac{e_{\text {estimation }}(h) \cdot\left[1-e_{\text {estimation }}(h)\right]}{\left|S_{1}\right|}+\frac{e_{\text {estimation }}(j) \cdot\left[1-e_{\text {estimation }}(j)\right]}{\left|S_{2}\right|} \\
& \sigma=\sqrt{\frac{0.15(1-0.15)}{30}+\frac{0.25(1-0.25)}{5000}}=0,0655 \ldots
\end{aligned}
$$

## Evaluation Example

- With probability 0.95 , the confidence interval is:

$$
d_{\text {true }} \in\{0.1-0,0655 ; 0.1+0,0655\}
$$

- The confidence interval does not contain 0 :
- The difference is statistically significant


## Methods for model evaluation

o Hold-out


## Methods for model evaluation

- Hold-out
o Pros:
- Fast evaluation
- Cons:
- Only one experiment $\rightarrow$ low statistical relevance


## Methods for model evaluation

- Repeated Hold-out with random sub-sampling
o Choose n
- ResultList = \{ \}
- For $1<i<n$
- Random Sampling of (with or without replacement):
- Training set
- Validation set
- Test set
- Model = buildModel(Training set, Validation set)
- ResultList.add(evaluateModel(Model, Test set))
- Return avg(ResultList)


## Methods for model evaluation

- Repeated Hold-out with random sub-sampling
- Pros:
- More statistical significance
- Cons:
- Slow evaluation
- Not all the tuples are involved in the training and evaluation phase


## Methods for model evaluation

o k-fold Cross Validation

- Choose k
- Divide the whole dataset D in k folds (portion)
- ResultList = \{ \}
- For $1<i<k$
- Build Training set = D \fold
- Random sample the Validation Set from the Training Set
- Training set = Training set \Validation Set
- Test set = fold ${ }_{i}$
- Model = buildModel(Training set, Validation set)
- ResultList.add(evaluateModel(Model, Test set))
- Return avg(ResultList )


## Methods for model evaluation

o k-fold Cross Validation
o Pros:

- Good statistical significance
- the greater is $k$ the better the significance - If $k=|D|$ Cross Validation is called leave-one-out evaluation
o Cons:
- Very slow evaluation
- The k-fold Cross Validation needs to be stratified:
- Each fold has to keep the same statistical properties of the whole datase $\dagger$


## Evaluation Metrics

- The focus is on the predictive quality of a model
- instead of computational cost, scalability...
- Confusion Matrix

| Actual class | Predicted class |  |  |
| :---: | :--- | :--- | :--- |
|  |  | Class = Yes | Class = No |
|  | Class = Yes | True Positive <br> (TP) | False Negative <br> (FN) |
|  | Class = No | False Positive <br> (FP) | True Negative <br> (TN) |

## Global Accuracy

- Global Accuracy

$$
\text { accuracy }=\frac{T P+T N}{T P+F N+F P+T N}
$$

- The number of all the well-predicted observation over the cardinality of the data set


## Global Accuracy Limits

- Is a global accuracy of $99.9 \%$ good?
o Example:
- Binary Classification
- \#records of class $0=9990$
- \# records of class 1 = 10
- A classifier that predicts always 0 :
- Global Accuracy = 99.9\%
- But the model is useless!


## Cost Matrix

- Similar to the confusion matrix

| Actual class | Predicted class |  |  |
| :---: | :--- | :--- | :--- |
|  | $\mathrm{C}(\mathbf{i} \mid \mathrm{j})$ | Class = Yes | Class = No |
|  | Class = Yes | C(Yes $\mid$ Yes) | C(No\|Yes) |
|  | Class = No | C(Yes $\mid$ No) | C(No \|No) |

- $C(i \mid j)$ is the cost of predicting a record as class $i$ when the actual class is $j$

\section*{Cost Evaluation of 2 Models (M1, M2) <br> | Cost | Predicted class |  |  |
| :---: | :---: | :---: | :---: |
| Actual class | C(i\|j) | Yes | No |
|  | Yes | -1 | 100 |
|  | No | 1 | 0 |


| Confusion <br> Matrix M1 | Predicted class |  |  |
| :---: | :--- | :---: | :---: |
|  | $\mathrm{C}(\mathrm{i} \mid \mathrm{j})$ | Yes | No |
|  | Yes | 150 | 40 |
|  | No | 60 | 250 |

Accuracy: 0.9
Cost: 3910

| Confusion <br> Matrix M2 | Predicted class |  |  |
| :---: | :--- | :---: | :---: |
| Actual <br> Class | $\mathrm{C}(\mathrm{i} \mid \mathrm{j})$ | Yes | No |
|  | Yes | 250 | 45 |
|  | No | 5 | 200 |

Cost: 4255

## Cost-sensitive Measures

- For each class
- Precision: the confidence of model
- How much can I trust a prediction?

$$
\text { precision }=\frac{T P}{T P+F P}
$$

- Recall: the coverage of a model
- How many records of a specific class can my model correctly predict?

$$
\text { recall }=\frac{T P}{T P+F N}
$$

- F1-Measure: harmonic mean of precision and recall

$$
F_{1}-\text { Measure }=\frac{2 \cdot \text { precision } \cdot \text { recall }}{\text { precision }+ \text { recall }}
$$

- Binary Classification
- \#records of class $0=9990$
o \# records of class 1 = 10
- A classifier that predicts always 0:
- Global Accuracy $=0.999$
- Precision of class 1: NaN ( 0 / 0)
- Recall of class 1:0
o Precision of class 0: 0.999
- Recall of class 0: 1


## ROC (Receiver Operating Characteristic)

- The ROC curve is a graphical plot that illustrates the performance of a binary classifier system as its discrimination threshold is varied


$$
\begin{aligned}
& T P R=\text { recall }=\frac{T P}{T P+F N} \\
& F P R=\frac{F P}{T N+F P}
\end{aligned}
$$

## Threshold

- Given a binary classifier the following rule holds:

$$
\begin{aligned}
& \operatorname{Pr}(C=y e s \mid \bar{t}) \geq \operatorname{Pr}(C=n o \mid \bar{t}) \Rightarrow C=\text { yes } \\
& \operatorname{Pr}(C=\text { yes } \mid \bar{t}) \geq 1-\operatorname{Pr}(C=\text { yes } \mid \bar{t}) \Rightarrow C=\text { yes } \\
& 2 \cdot \operatorname{Pr}(C=y e s \mid \bar{t}) \geq 1 \Rightarrow C=\text { yes } \\
& \operatorname{Pr}(C=\text { yes } \mid \bar{t}) \geq 0.5 \Rightarrow C=\text { yes }
\end{aligned}
$$

## Threshold

- What happens if we vary the threshold value?


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- For each prediction we have a confusion matrix


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- For each confusion matrix we have a FPR and a TPR


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- What happens if we vary the threshold value?
- For each threshold we have a different classification rule
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- For each confusion matrix we have a FPR and a TPR
- For each FPR and TPR we have a point in the ROC space


## Threshold

- What happens if we vary the threshold value?
o For each threshold we have a different classification rule
- For each rule we have a prediction
- For each prediction we have a confusion matrix
- For each confusion matrix we have a FPR and a TPR
- For each FPR and TPR we have a point in the ROC space
- Examples:

$$
\begin{gathered}
\operatorname{Pr}(C=y e s \mid \bar{t}) \geq 0.3 \Rightarrow C=\text { yes } \\
\operatorname{Pr}(C=y e s \mid \bar{t}) \geq 0.75 \Rightarrow C=\text { yes }
\end{gathered}
$$

## How to build a ROC curve

| Instance | $\mathrm{P}(+\mid \mathrm{x})$ | True <br> Class |
| :---: | :---: | :---: |
| 1 | 0.95 | + |
| 2 | 0.93 | + |
| 3 | 0.87 | - |
| 4 | 0.85 | - |
| 5 | 0.85 | - |
| 6 | 0.85 | + |
| 7 | 0.76 | - |
| 8 | 0.53 | + |
| 9 | 0.43 | - |
| 10 | 0.25 | + |

- Sort the records according to $P(+\mid x)$ [Descendent]
- Each $P(+\mid x)$ will be a threshold
o For each threshold, compute the confusion matrix
- Compute FPR and TPR

\[\)|  Class  | + | - | + | - | - | - | + | - | + | + |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | |  TP  | 5 | 4 | 4 | 3 | 3 | 3 | 3 | 2 | 2 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  FP  | 5 | 5 | 4 | 4 | 3 | 2 | 1 | 1 | 0 | 0 |
|  TN  | 0 | 0 | 1 | 1 | 2 | 3 | 4 | 4 | 5 | 5 |
|  FN  | 0 | 1 | 1 | 2 | 2 | 2 | 2 | 3 | 3 | 4 |
|  TPR  | 1 | 0.8 | 0.8 | 0.6 | 0.6 | 0.6 | 0.6 | 0.4 | 0.4 | 0.2 |
|  FPR  | 1 | 1 | 0.8 | 0.8 | 0.6 | 0.4 | 0.2 | 0.2 | 0 | 0 |

\]



## How to evaluate a ROC curve



## How to evaluate a ROC curve



High-precision zone

## How to evaluate a ROC curve



High-precision zone

## How to evaluate a ROC curve

Best Point



## How to evaluate a ROC curve



## ROC comparison

- The greater the area under the curve the better the quality of the model



## ROC comparison


o Which is
better?

## ROC comparison


o Which is better?
o If we are interested in precision?

## ROC comparison


o Which is better?
o If we are interested in precision?
o If we are interested in recall?


## Confusion Matrix Glossary



## true positive (TP)

eqv. with hit

## true negative (TN)

eqv. with correct rejection

## false positive (FP)

eqv. with false alarm, Type I error

## false negative (FN)

eqv. with miss, Type II error
sensitivity or true positive rate (TPR)
eqv. with hit rate, recall
$T P R=T P / P=T P /(T P+F N)$
specificity (SPC) or true negative rate (TNR)
$S P C=T N / N=T N /(F P+T N)$
precision or positive predictive value (PPV)
$P P V=T P /(T P+F P)$
negative predictive value (NPV)
$N P V=T N /(T N+F N)$
fall-out or false positive rate (FPR
$F P R=F P / N=F P /(F P+T N)$
false discovery rate (FDR)
$F D R=F P /(F P+T P)=1-P P V$
Miss Rate or False Negative Rate (FNR)
$F N R=F N / P=F N /(F N+T P)$

$$
\begin{aligned}
& \text { accuracy (ACC) } \\
& \quad A C C=(T P+T N) /(P+N)
\end{aligned}
$$

F1 score
is the harmonic mean of precision and sensitivity
$F 1=2 T P /(2 T P+F P+F N)$
Matthews correlation coefficient (MCC)

$$
\frac{T P \times T N-F P \times F N}{\sqrt{(T P+F P)(T P+F N)(T N+F P)(T N+F N)}}
$$

Informedness $=$ Sensitivity $\boldsymbol{+}$ Specificity $\mathbf{- 1}$
Markedness $\boldsymbol{=}$ Precision + NPV - 1
Sources: Fawcett (2006) and Fowers (2011). [2][3]

